

Cvičení: Vypočtěte determinanty daných matic

```
[> restart;
[> with(linalg):
```

a)

```
[> Ma:=matrix([[2,-1],[-4,3]]);
[> det(Ma);
[>
```

$$Ma := \begin{bmatrix} 2 & -1 \\ -4 & 3 \end{bmatrix}$$
$$2$$

b)

```
[> Mb:=matrix([[0,1,-2],[-1,0,3],[2,-3,0]]);
[> det(Mb);
[> gausselim(Mb);
[>
```

$$Mb := \begin{bmatrix} 0 & 1 & -2 \\ -1 & 0 & 3 \\ 2 & -3 & 0 \end{bmatrix}$$
$$0$$
$$\begin{bmatrix} -1 & 0 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$$

c)

```
[> Mc:=matrix([[1,2,3],[2,5,8],[3,8,10]]);
[> det(Mc);
[>
```

$$Mc := \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 8 \\ 3 & 8 & 10 \end{bmatrix}$$
$$-3$$

d)

```
[> Md:=matrix([[0,1,-1],[-2,1,3],[2,7,-8]]);
[> det(Md);
[>
```

$$Md := \begin{bmatrix} 0 & 1 & -1 \\ -2 & 1 & 3 \\ 2 & 7 & -8 \end{bmatrix}$$
$$6$$

e)

```
[> Me:=matrix([[5,-1,0,2],[0,3,-1,5],[0,0,-4,2],[0,0,0,3]]);
[> det(Me);
[>
```

$$Me := \begin{bmatrix} 5 & -1 & 0 & 2 \\ 0 & 3 & -1 & 5 \\ 0 & 0 & -4 & 2 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$
$$-180$$

f)

```
[> Mf:=matrix([[1,-2,1,4],[2,-4,0,0],[3,-4,2,5],[0,2,-4,-9]]);
[>
```

$$Mf := \begin{bmatrix} 1 & -2 & 1 & 4 \\ 2 & -4 & 0 & 0 \\ 3 & -4 & 2 & 5 \\ 0 & 2 & -4 & -9 \end{bmatrix}$$

```

[> det(Mf);
[> gausselim(Mf);
[> Mg:=matrix([[2,1,-1],[0,4,3],[3,2,-2]]);
```

$$\begin{bmatrix} 1 & -2 & 1 & 4 \\ 0 & 2 & -1 & -7 \\ 0 & 0 & -2 & -8 \\ 0 & 0 & 0 & 10 \end{bmatrix}$$

g)

```

[> Mg:=matrix([[2,1,-1],[0,4,3],[3,2,-2]]);
```

$$Mg := \begin{bmatrix} 2 & 1 & -1 \\ 0 & 4 & 3 \\ 3 & 2 & -2 \end{bmatrix}$$

```

[> det(Mg);
[> -7
```

h)

```

[> Mh:=matrix([[-1,2,1],[1,3,2],[-4,1,2]]);
```

$$Mh := \begin{bmatrix} -1 & 2 & 1 \\ 1 & 3 & 2 \\ -4 & 1 & 2 \end{bmatrix}$$

```

[> det(Mh);
[> -11
```

i)

```

[> Mi:=matrix([[2,4,-3],[-2,1,0],[5,-2,4]]);
```

$$Mi := \begin{bmatrix} 2 & 4 & -3 \\ -2 & 1 & 0 \\ 5 & -2 & 4 \end{bmatrix}$$

```

[> det(Mi);
[> 43
```

j)

```

[> Mj:=matrix([[4,0,0],[-2,cos(x),-sin(x)],[5,sin(x),cos(x)]]);
[> Mj := \begin{bmatrix} 4 & 0 & 0 \\ -2 & \cos(x) & -\sin(x) \\ 5 & \sin(x) & \cos(x) \end{bmatrix}


```

[> det(Mj);
[> 4 \cos(x)^2 + 4 \sin(x)^2
[>
```


```