

On using automated deduction techniques in dynamic geometry environments

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What is Dynamic Geometry (DG)?

Models built by computer software that can be changed dynamically

King and Schattschneider (1997)

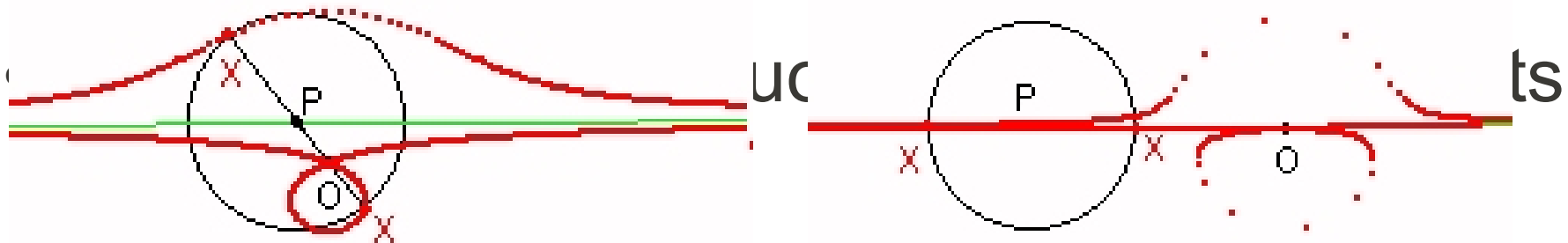
Properties of dynamical models

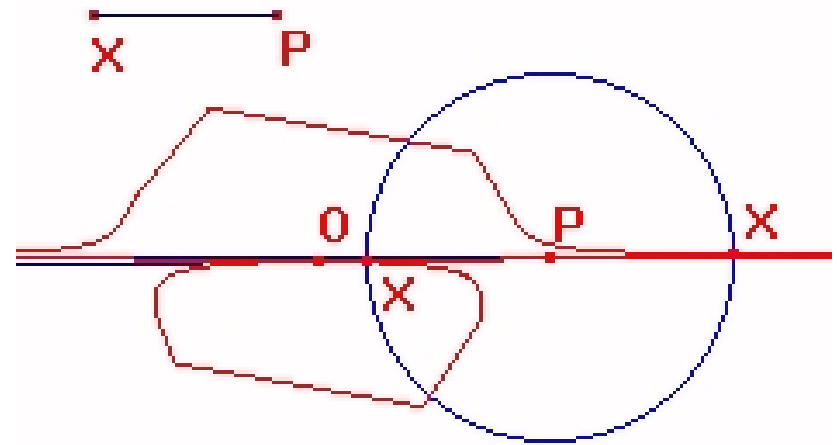
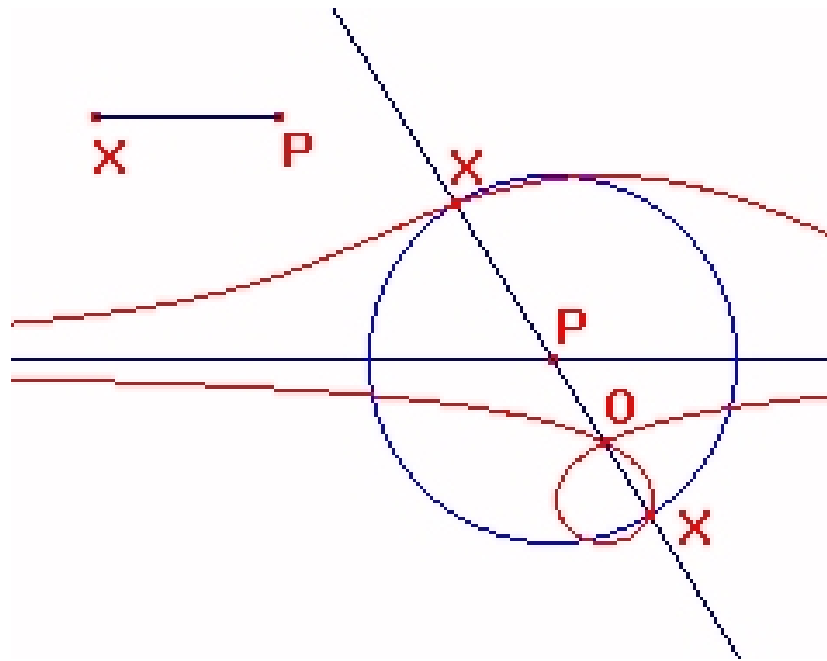
- Dynamic transformations
- Dynamic measurement
- Free dragging
- Animation
- Locus generation

Common strategy for tracing loci

In order to trace the locus of an object X , depending somehow on another object P :

- Select the object P , the *driver object*, which must lie on a predefined path
- Sample the path and plot X for each sample





$P(x_1, x_2)$ lies on the x axis:

$$x_2 = 0$$

$O(0, -1)$ is a fixed point

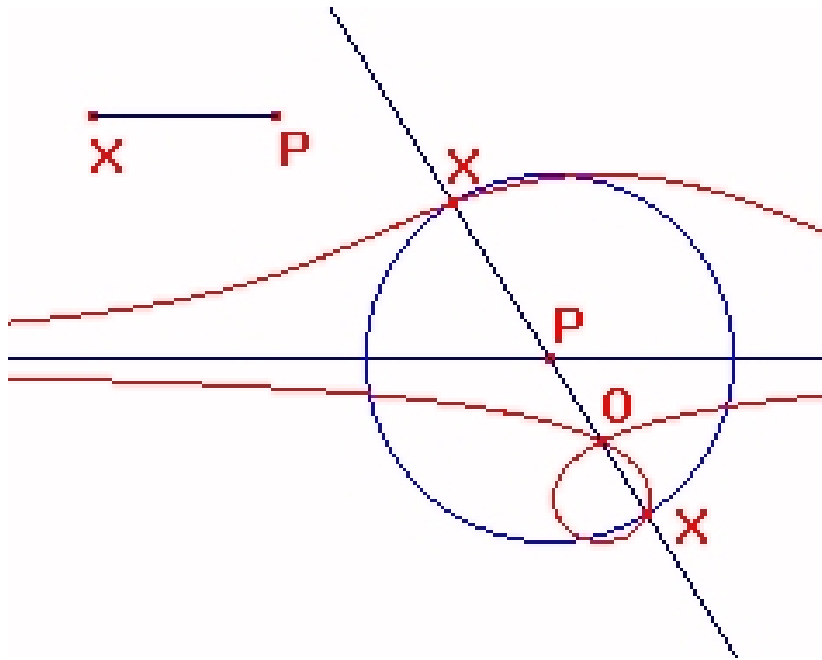
$X(u, v)$ lies on the line OP :

$$(v+1)/u = 1/x_1$$

and on the circle (P, XP) :

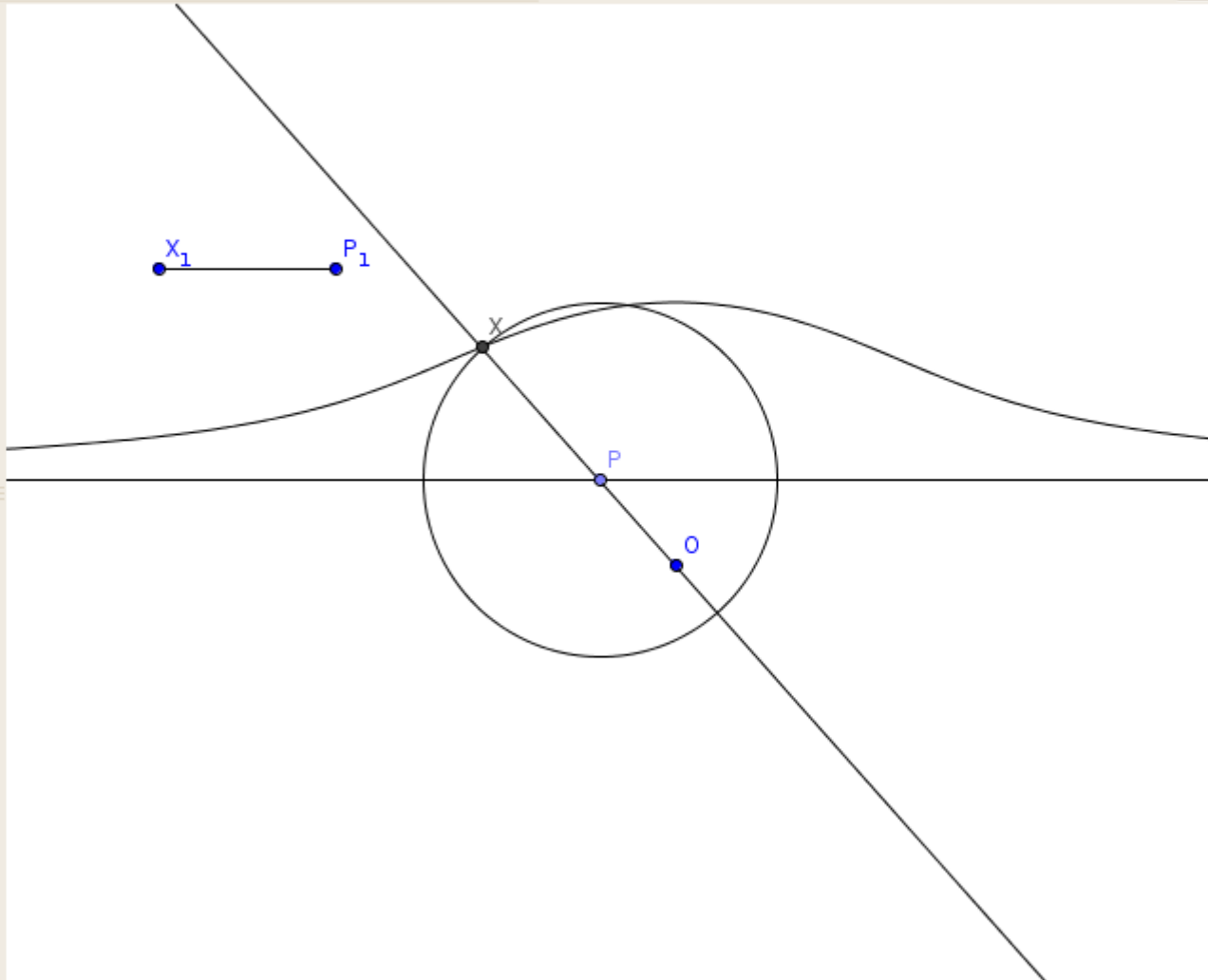
$$(u-x_1)^2 + v^2 = d^2$$

Eliminating x_1 in the above equations we get the conchoid's equation!



Elige y Mueve
Arrastrar o seleccionar objetos (Esc)

- Objetos Libres
 - A = (-2.24, 1.3)
 - B = (6.1, 1.3)
 - O = (2.74, 0.4)
 - P₁ = (-0.84, 3.52)
 - X₁ = (-2.7, 3.52)
- Objetos Dependientes
 - P = (1.94, 1.3)
 - X = (0.7, 2.69)
 - a: y = 1.3
 - b = 1.86
 - c: $(x - 1.94)^2 + (y - 1.3)^2 = 3.4$
 - d: $0.9x + 0.8y = 2.79$



Entrada: Comando ...

LADucation *for* GeoGebra

The *one-click* version of LAD for education

- Equations and graphs of geometric loci
- *Certified* answers to yes/no questions
- Remotely computed using symbolic algebraic techniques from the field of Automated Deduction
- Sound Mathematics that complement the graphing abilities of GeoGebra

Just upload the GeoGebra file with your locus or question

[Instructions](#)

Main

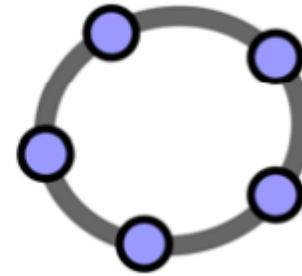
Instructions

Examples

Contact

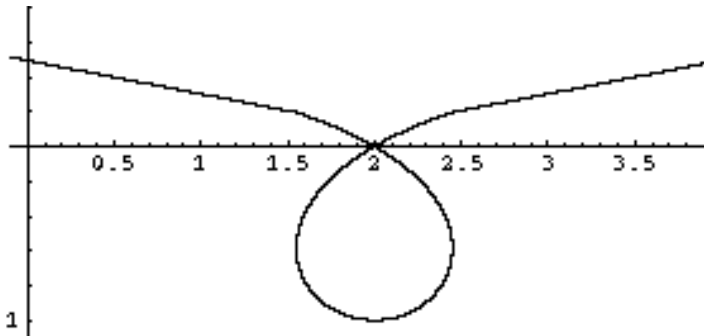
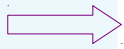
GeoGebra Help

Official Manual 3.2



Continuity

GeoGebra allows you to turn the continuity heuristic *On* or *Off* in the *Options* menu. The software uses a near-to-heuristic to keep moving intersection points (e. g., line-conic, conic-conic) close to their old positions and avoid jumping intersection points.



The locus equation is

$$4 - 4x + x^2 - 8y + 8xy - 2x^2y + y^2 - 4xy^2 + x^2y^2 - 2y^3 + y^4 == 0$$

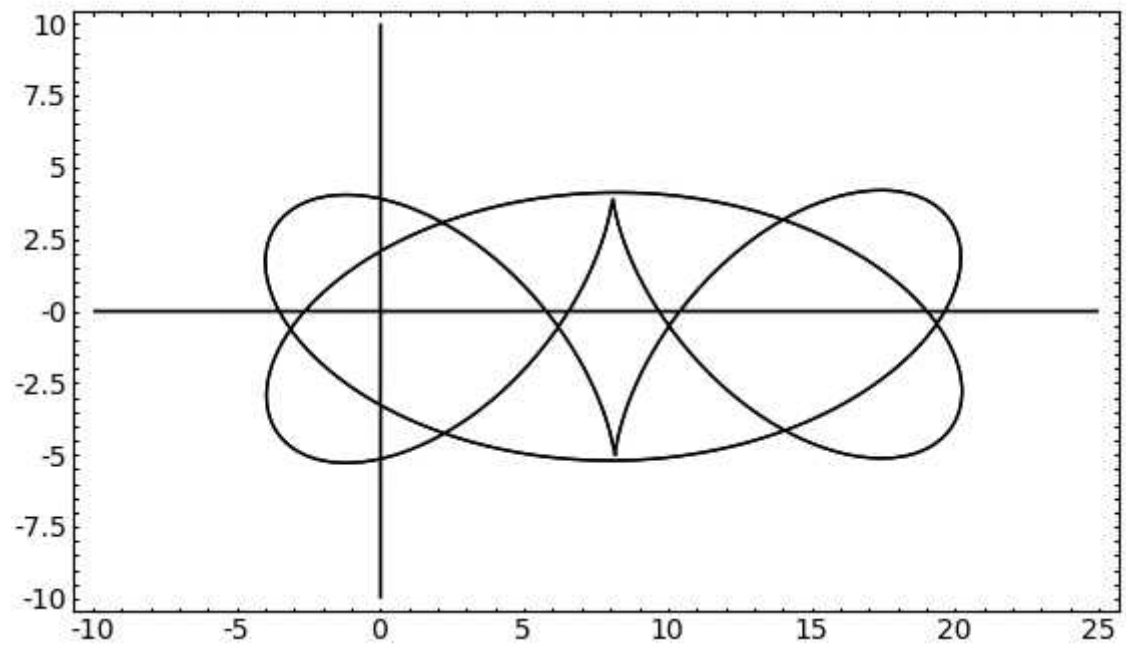
GeoGebra & Google Summer of Code 2010

Locus line equation

Find the equation for a locus line constructed in GeoGebra. The goal is an integrated solution that doesn't require upload of a ggb file to a server.

Contour and Implicit Plotting

Implement contour and implicit plotting routines in GeoGebra.

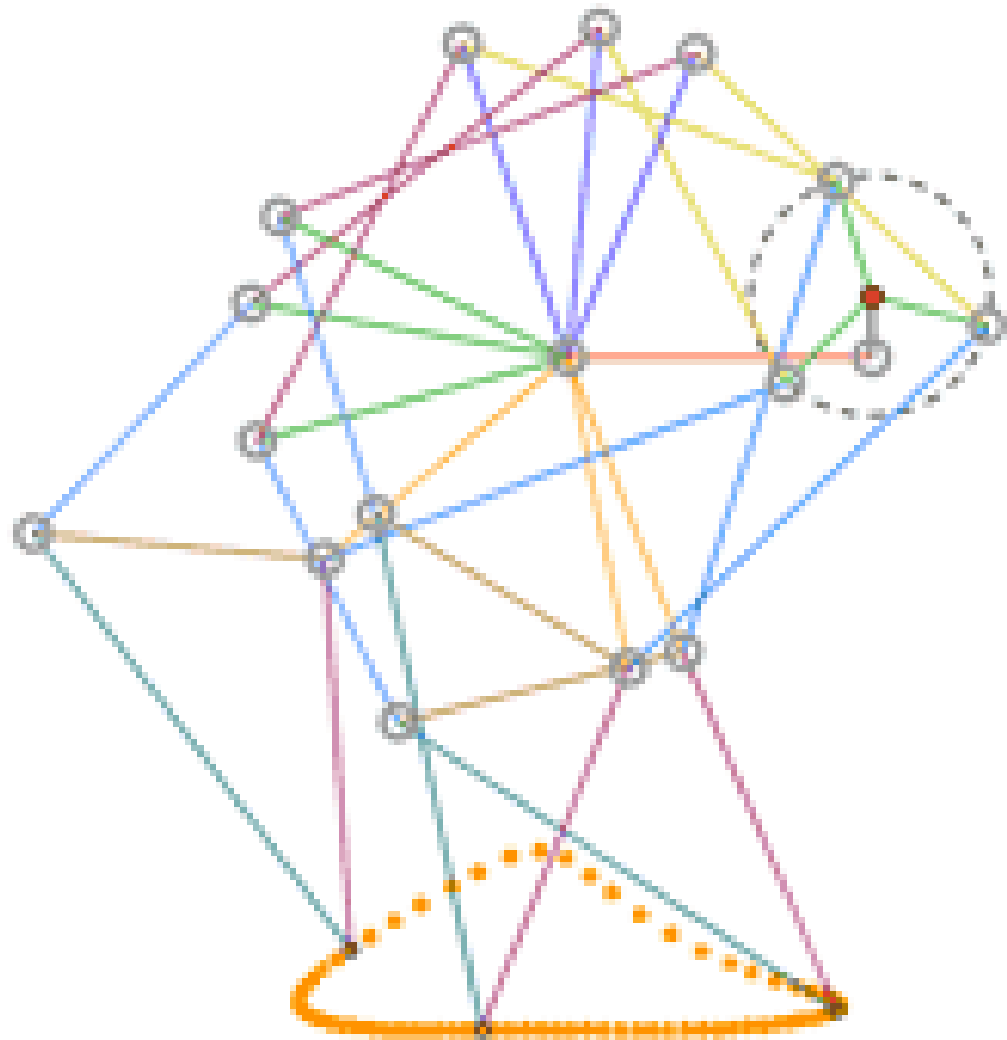


$$\begin{aligned}
& 80232964351695482090052668589141175946115160321 + \\
& 2707034858032029512277843872719719601534605600*x - \\
& 12094748935307324983015398495218909628691240000*x^2 + \\
& 1361919898426493638759337505309527108856000000*x^3 + \\
& 394154177587603756005838424500972080600000000*x^4 - \\
& 104626220355981452458120738564213200000000000*x^5 + \\
& 958195954477407572195322135494000000000000*x^6 - \\
& 39253765735440433237389630000000000000000*x^7 + \\
& 6045758945856809497506250000000000000000*x^8 - \\
& \quad \quad \quad \text{(30 terms)} \\
& 259194873707747255849994000000000000000000*y^7 + \\
& 6045758945856809497506250000000000000000*y^8=0
\end{aligned}$$

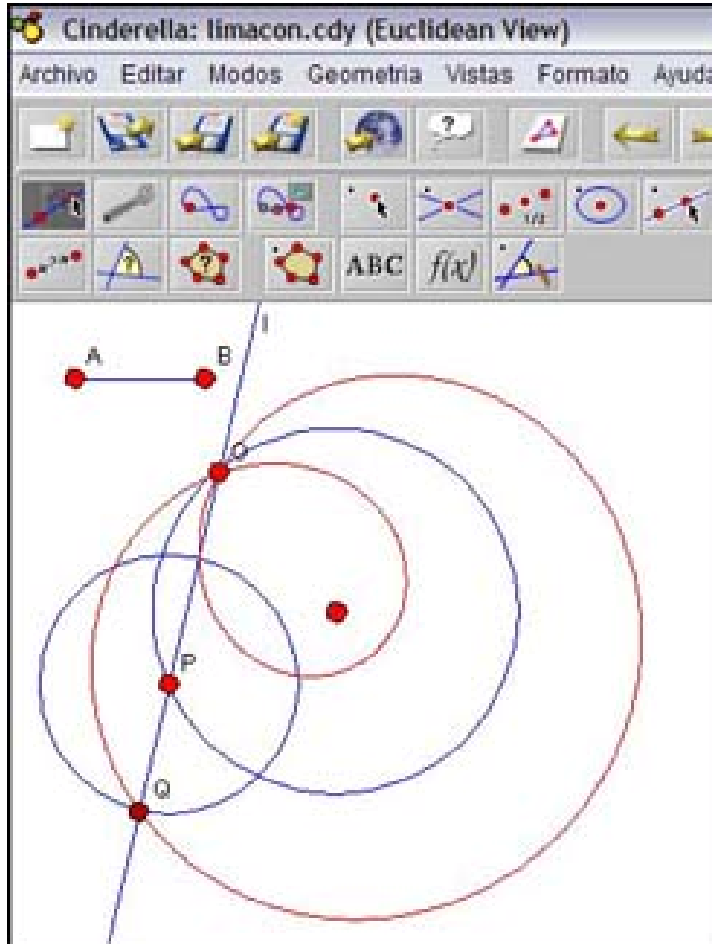
Should we hide this (kind of) result to students?

A case of failure



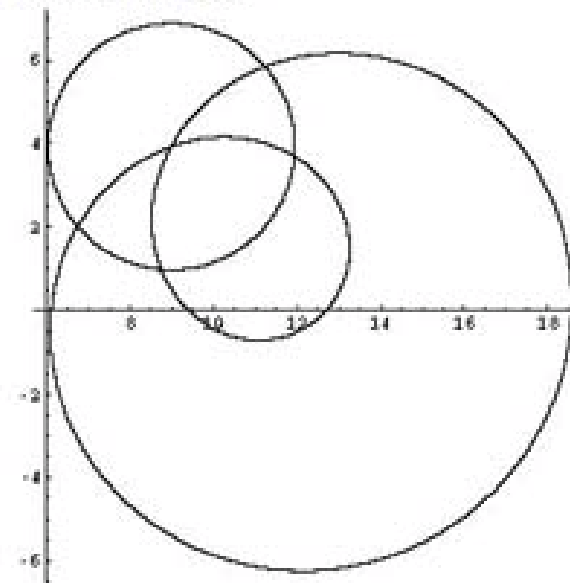


Loci and degenerated conditions

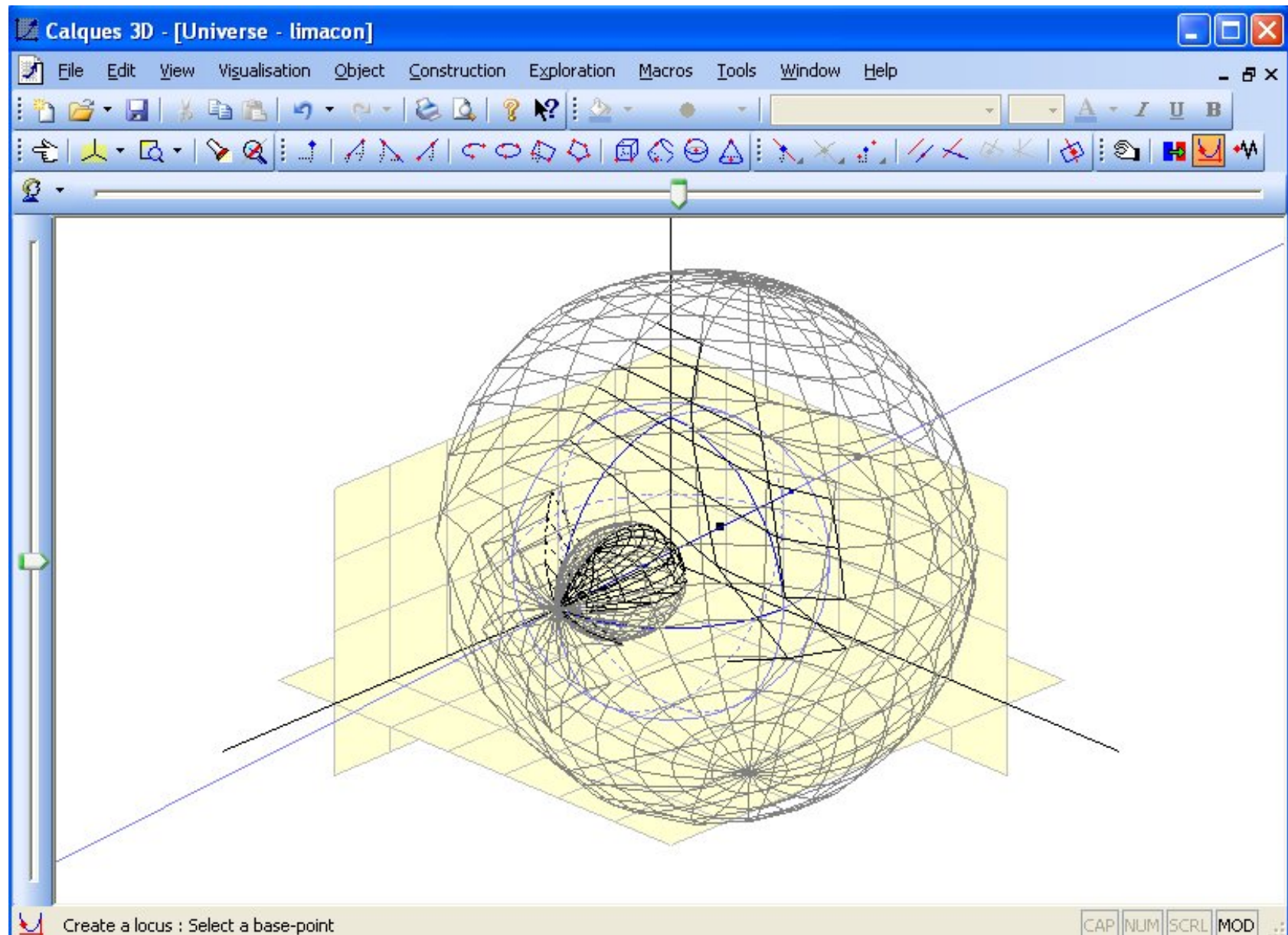


the circle $21871 - 4495 \cdot x + 250 \cdot x^2 - 1960 \cdot y + 250 \cdot y^2 == 0$
 the quartic $169480016762 - 68233056625 \cdot x + 9735246250 \cdot x^2 - 585000000 \cdot x^3 +$
 $12500000 \cdot x^4 - 3586455700 \cdot y + 865800000 \cdot x \cdot y - 37000000 \cdot x^2 \cdot y +$
 $2918126250 \cdot y^2 - 585000000 \cdot x \cdot y^2 + 25000000 \cdot x^2 \cdot y^2 - 37000000 \cdot y^3 +$
 $12500000 \cdot y^4 == 0$

The locus is (or is contained in)
 EXACT PICTURE



Extension to 3D



```
Range[-2.7,2.8,-4.4,2.8,-2.7,2.7];  
FreePointD[Pt1,1,1,0];  
FreePointD[Pt2,-31/49,16/9,0];  
SphereD[Sp3,Pt1,Pt2];  
PointOnSphere[Pt4,Sp3];  
LineD[Ln5,Pt2,Pt4];  
SphereD[Sp6,Pt4,Pt1];  
Intersection1LineSphere[Pt8,Sp6,Ln5];  
Intersection2LineSphere[Pt9,Sp6,Ln5];  
Locus[O10,Pt8,Pt4];
```

OpenMath

Extending the 3dgeo experimental CDs
Requiring 3d-DGS developers OM-export

3D Automatic Discovery using CoCoA



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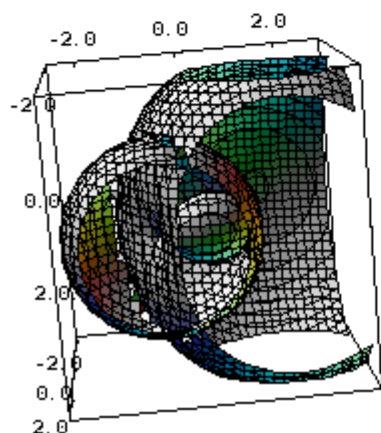
The locus of Pt8 in the given construction is

the sphere $441x^2 + 558x + 441y^2 + 441z^2 - 1568y + 128 = 0$

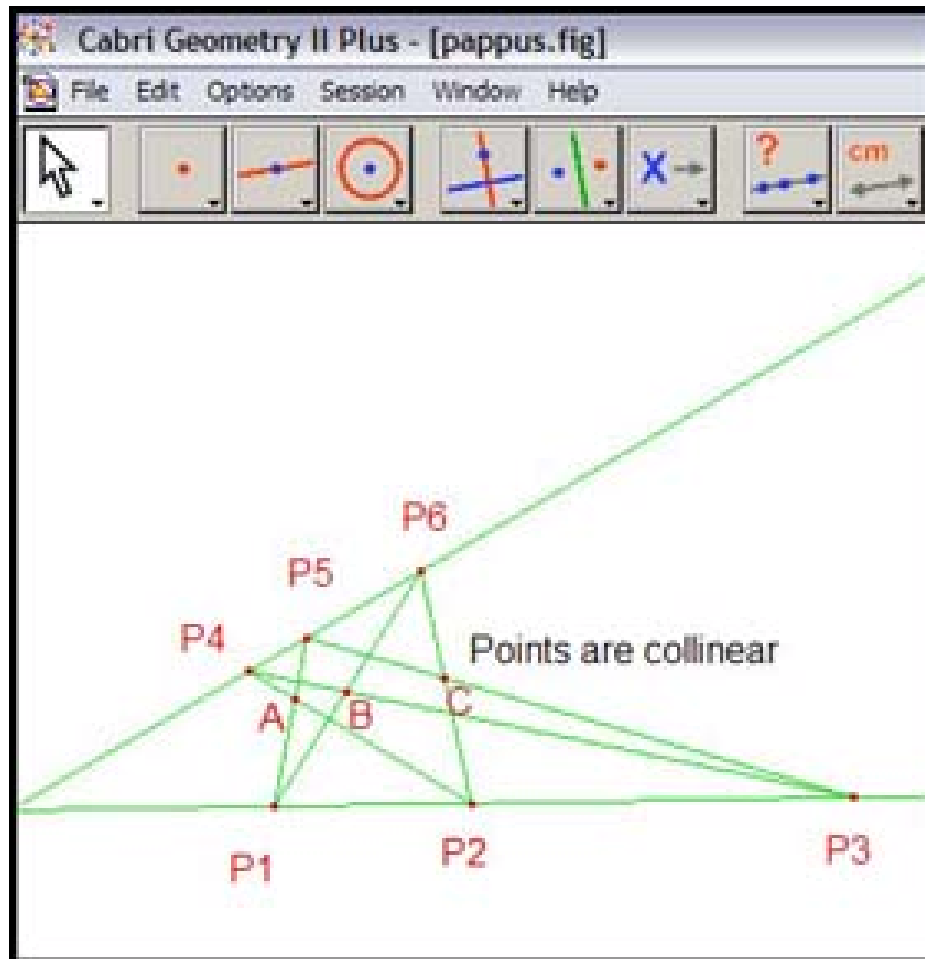
and $85766121x^4 - 343064484x^3 + 171532242y^2x^2 + 171532242z^2x^2 - 343064484yx^2 -$

$155363859x^2 - 343064484y^2x - 343064484z^2x + 686128968yx + 80946126x + 85766121y^4 + 85766121z^4 -$

$343064484y^3 - 155363859y^2 + 171532242y^2z^2 - 343064484yz^2 - 498428343z^2 + 1433186300y - 860340224 = 0$



Proof

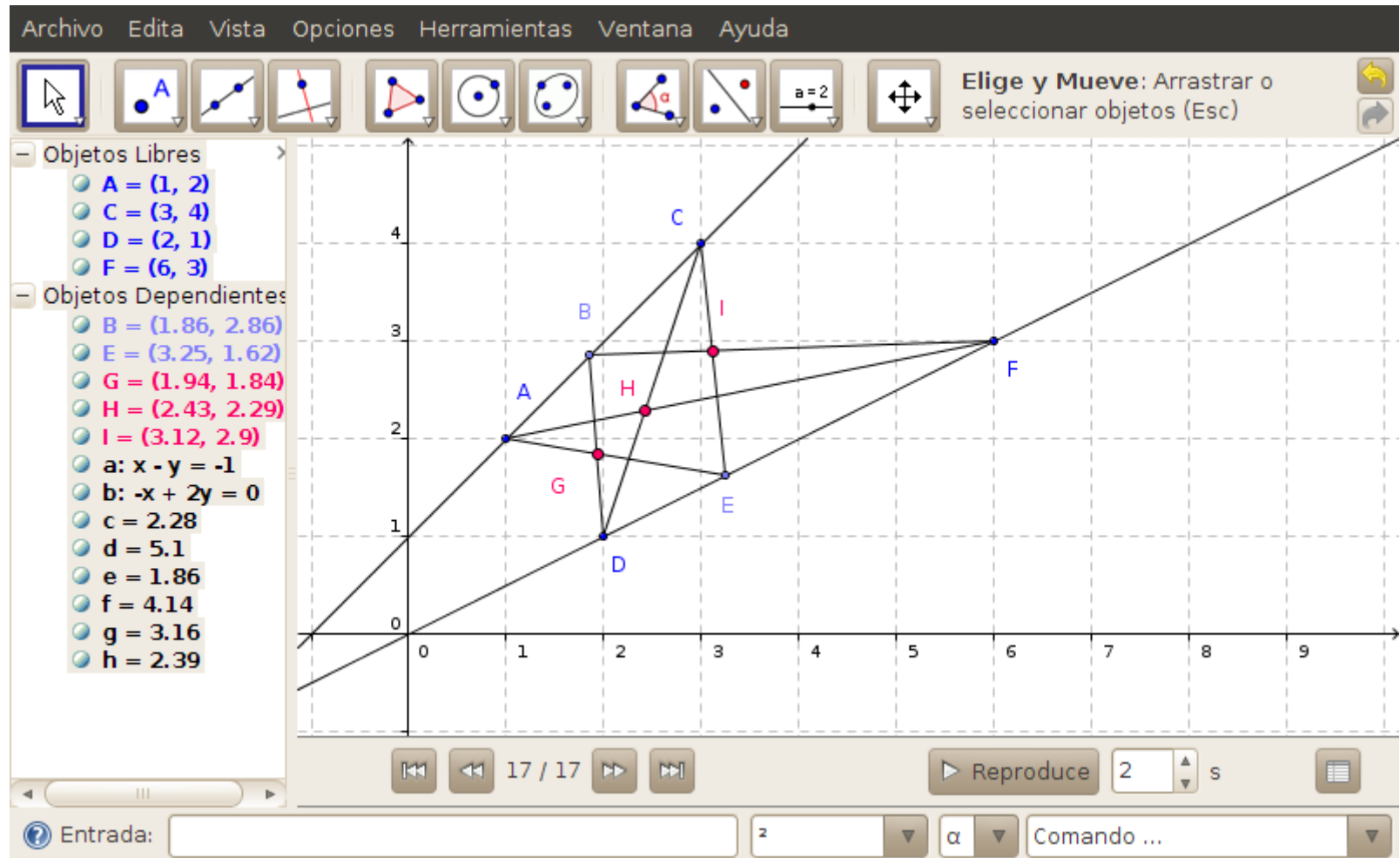


Given a construction with points
 $P4(-469/100, 21/100)$
 $P6(-274/100, 134/100)$
 $P1(-445/100, -111/100)$
 $P3(210/100, -1)$
 $P5(x[1], x[2])$
 $P2(x[3], x[4])$
 $A(x[5], x[6])$
 $B(x[7], x[8])$
 $C(x[9], x[10])$

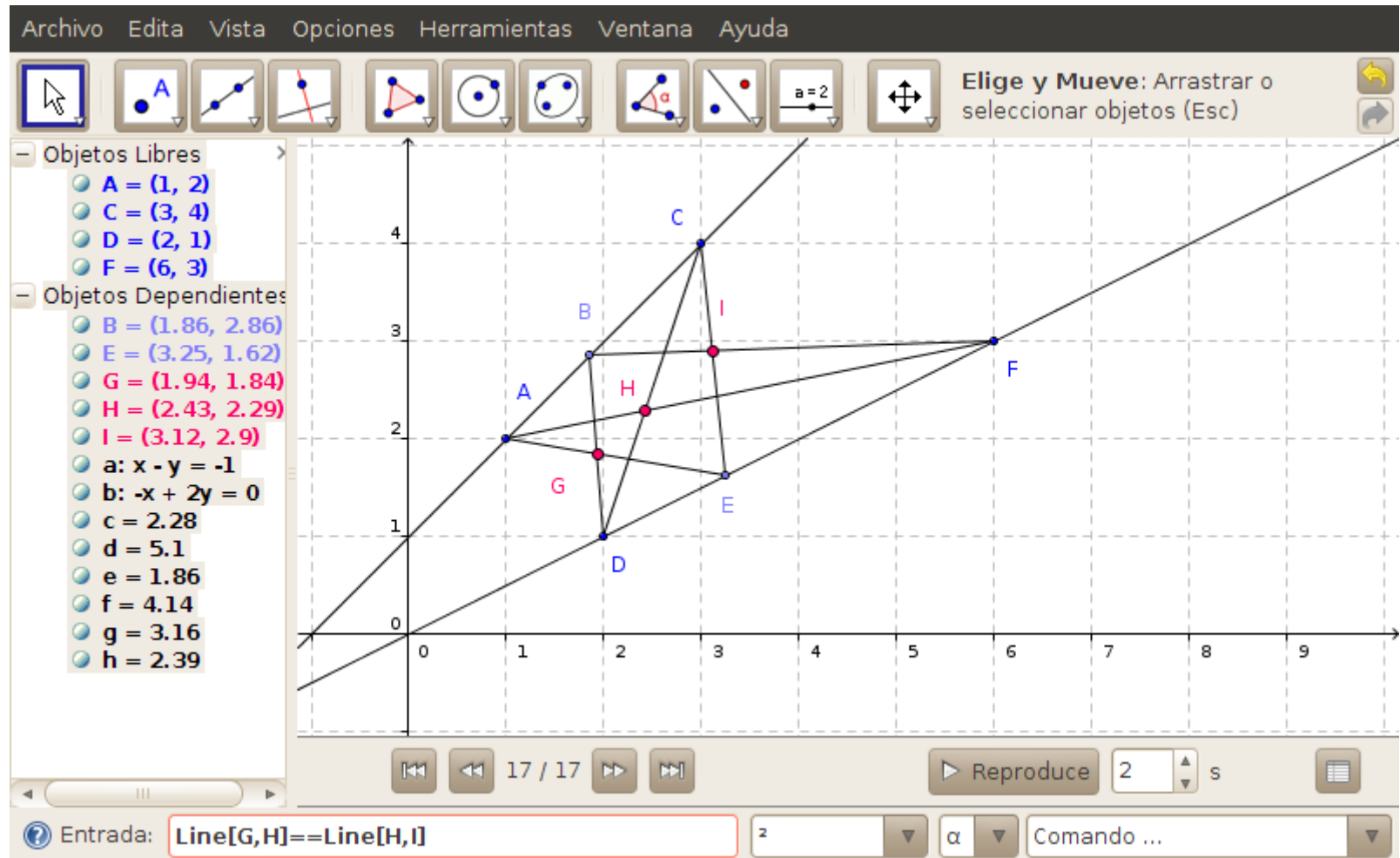
with constraints
 $\text{Aligned}(P5, P4, P6)$
 $\text{Aligned}(P2, P1, P3)$
 $\text{Aligned}(A, P5, P1)$
 $\text{Aligned}(A, P2, P4)$
 $\text{Aligned}(B, P4, P3)$
 $\text{Aligned}(B, P6, P1)$
 $\text{Aligned}(C, P5, P3)$
 $\text{Aligned}(C, P6, P2)$

the statement
 $\text{Aligned}(A, B, C)$
is true

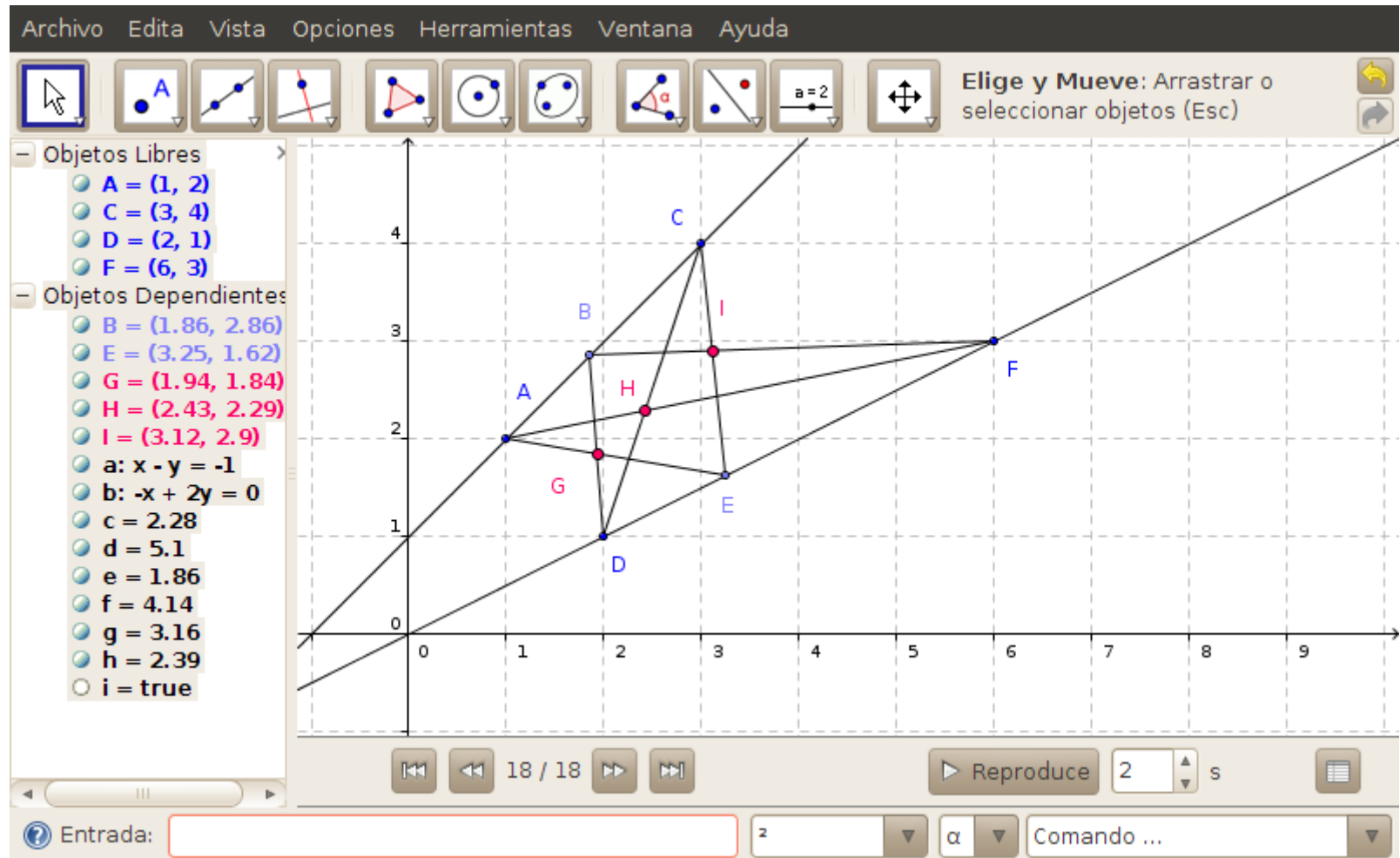
Proof



Proof



Proof





LADucation *for* GeoGebra

[Main](#)

[Instructions](#)

[Examples](#)

[Contact](#)

**Your Geogebra file Pappus.ggb has been successfully uploaded.
It will be processed in 8 seconds.**

Given a construction with points

A(1.,2.)

C(3.,4.)

D(2.,1.)

F(6.,3.)

B(x[1],x[2])

E(x[3],x[4])

H(x[5],x[6])

G(x[7],x[8])

I(x[9],x[10])

and with constraints

Aligned(B,A,C)

Aligned(E,D,F)

Aligned(H,A,F)

Aligned(H,C,D)

Aligned(G,A,E)

Aligned(G,B,D)

Aligned(I,B,F)

Aligned(I,C,E)

the statement

Aligned(G,H,I)

is true (except in certain degenerate cases)

Proof

(roughly) A proposition is declared to be True if

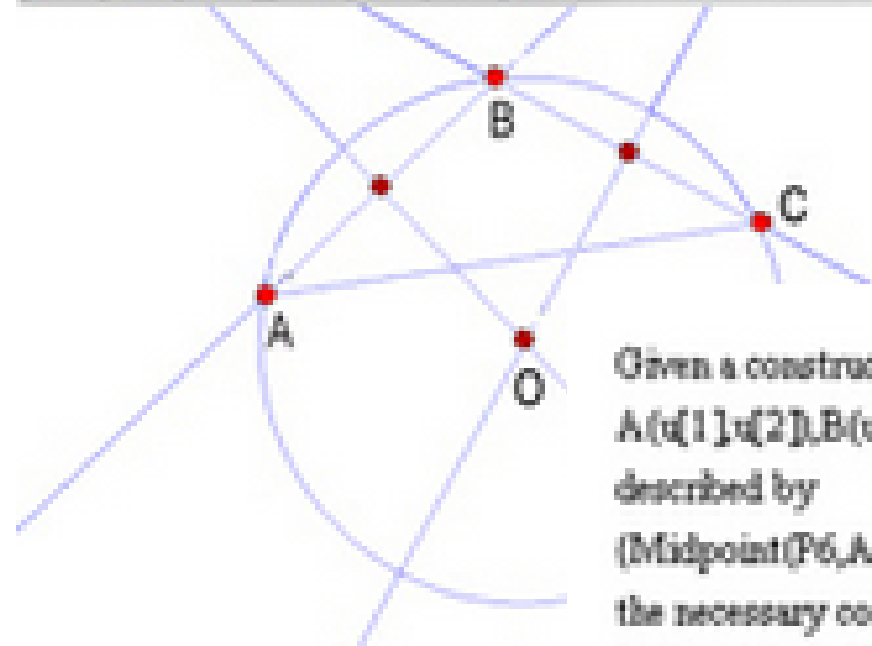
(any component of)

the hypotheses ideal is contained in the thesis ideal.

Be careful, this holds in the complex field, not **always** in the real one.

$$\text{Sat}(H, \text{Sat}(H, T)) \Leftrightarrow (1)$$

Discovery



Given a construction with points

$A(x_1, y_1), B(x_2, y_2), C(x_3, y_3), P_6(x_4, y_4), P_7(x_5, y_5), O(x_6, y_6)$,

described by

$\{ \text{Midpoint}(P_6, A, B), \text{Midpoint}(P_7, B, C), \text{Perpendicular}(O, P_6, A, B), \text{Perpendicular}(O, P_7, B, C) \}$,

the necessary condition(s) for

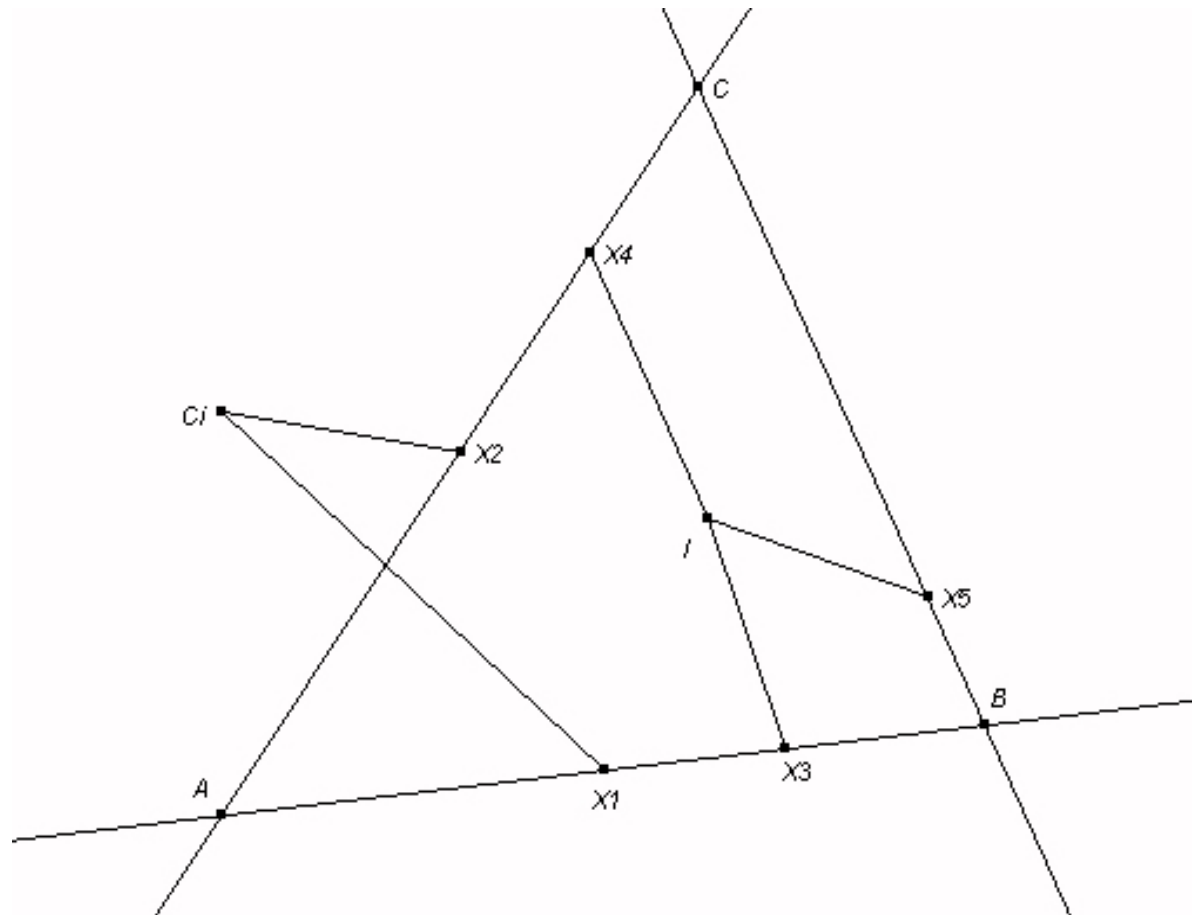
$\{ \text{Aligned}(A, O, C) \}$

is/are

$\{ \text{Perpendicular}(A, B, B, C) \} \vee \{ \text{Equal}(A, C) \}$



A formula from Euler

concerning the relation between the radii of the incircle, r , and the circumcircle, c , of a triangle, and the distance d between their centers.



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Given a construction with points
 $A(0,0), B(1,0), C(u[5],u[6]), X1(x[1],x[2]), X2(x[3],x[4]), X3(x[5],x[6]), X4(x[7],x[8]), X5(x[9],x[10]), I(u[7],u[8]), Ci(u[9],u[10])$,
described by
{Midpoint(X1,A,B), Midpoint(X2,A,C), Aligned(X3,A,B), Aligned(X4,A,C), Aligned(X5,B,C)},
the necessary condition(s) for
{Perpendicular(A,B,X1,Ci), Perpendicular(A,C,X2,Ci), Perpendicular(A,B,I,X3),
Perpendicular(A,C,I,X4), Perpendicular(B,C,I,X5), distance(I,X3)=distance(I,X4), distance(I,X3)=distance(I,X5)}
is(are)

$$2u(9) - 1 == 0 \wedge u(5)^2 - u(5) + u(6)^2 - 2u(6)u(10) == 0 \wedge ((\text{Aligned}\{A, B, C\}) \vee -u(7)^2 + 2u(5)u(7) + u(8)^2 - u(5) + 2u(6)u(8) - 4u(8)u(10) == 0) \wedge$$

$$((\text{Aligned}\{A, B, C\}) \vee 2u(7)u(6) - u(6) - 2u(5)u(8) - 2u(7)u(8) + 2u(8) == 0) \wedge$$

$$((\text{Aligned}\{A, B, C\}) \vee 2u(8)^3 - 8u(10)u(8)^2 + 2u(7)^2u(8) - 2u(7)u(8) - 2u(8) + u(6) == 0) \wedge$$

$$((\text{Aligned}\{A, B, C\}) \vee 2u(7)^3 - 3u(7)^2 + 2u(8)^2u(7) - 8u(8)u(10)u(7) - u(8)^2 + u(5) + 4u(8)u(10) == 0) \wedge$$

$$((\text{Aligned}\{A, B, C\}) \vee -4u(8)^4 + 16u(10)u(8)^3 - 8u(6)u(10)u(8)^2 + 4u(8)^2 - 4u(6)u(8) + u(6)^2 == 0) \wedge$$

$$((\text{Aligned}\{A, B, C\}) \vee -8u(7)u(8)^3 + 4u(8)^3 - 16u(5)u(10)u(8)^2 + 16u(7)u(10)u(8)^2 - 6u(5)u(8) + 2u(7)u(8) + 2u(8) + 2u(5)u(6) - u(6) == 0)$$

[Try another Discovery?](#)

$$d^4 - 2*d^2*c^2 - 4*r^2*c^2 + c^4$$

Dík
Gracias