

1.13 Klasifikace kvadrik - řešené příklady

Příklad 3: Vyšetřete kvadriku

$$3x^2 + 3y^2 + 3z^2 + 4\sqrt{2}xy + 2yz + 6x + 2y(2\sqrt{2}-1) - 6z - 9 = 0$$

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[ > restart;
[ > with(LinearAlgebra):
[ > with(linalg):
[ > with(plots):
[ > X:=Vector[row]([x,y,z,1]);
[ > X := [x, y, z, 1]
[ > K:=Matrix(a,1..4,1..4,shape=symmetric);
[ > K := 
$$\begin{bmatrix} a(1, 1) & a(1, 2) & a(1, 3) & a(1, 4) \\ a(1, 2) & a(2, 2) & a(2, 3) & a(2, 4) \\ a(1, 3) & a(2, 3) & a(3, 3) & a(3, 4) \\ a(1, 4) & a(2, 4) & a(3, 4) & a(4, 4) \end{bmatrix}$$

[ > Kv:=sort(expand(X.K.Transpose(X)),[x,y,z])=0;
[ Kv := a(1, 1)x^2 + 2a(1, 2)xy + 2a(1, 3)xz + a(2, 2)y^2 + 2a(2, 3)yz + a(3, 3)z^2
[ + 2a(1, 4)x + 2a(2, 4)y + 2a(3, 4)z + a(4, 4) = 0
[ > Tecna:=[x=m+t*u,y=n+t*v,z=p+t*w];
[ Tecna := [x = m + t u, y = n + t v, z = p + t w]
[ > Kv0:=simplify(eval(Kv,[x=m,y=n,z=p]));
[ Kv0 := a(1, 1)m^2 + 2a(1, 2)mn + 2a(1, 3)mp + a(2, 2)n^2 + 2a(2, 3)np + a(3, 3)p^2
[ + 2a(1, 4)m + 2a(2, 4)n + 2a(3, 4)p + a(4, 4) = 0
[ > Kv1:=simplify(eval(Kv,Tecna));
[ Kv1 := 2a(2, 3)np + 2a(1, 1)mtu + 2a(1, 2)mtv + 2a(1, 2)tun + 2a(1, 2)t^2uv
[ + 2a(1, 3)mtw + 2a(1, 3)tup + 2a(1, 3)t^2uw + 2a(2, 2)ntv + 2a(2, 3)ntw
[ + 2a(2, 3)tvp + 2a(2, 3)t^2vw + 2a(3, 3)ptw + a(1, 1)t^2u^2 + a(2, 2)t^2v^2
[ + a(3, 3)t^2w^2 + 2a(1, 4)tu + 2a(2, 4)tv + 2a(3, 4)tw + 2a(1, 2)mn + 2a(1, 3)mp
[ + a(1, 1)m^2 + a(2, 2)n^2 + a(3, 3)p^2 + 2a(1, 4)m + 2a(2, 4)n + 2a(3, 4)p + a(4, 4) = 0
[ > A:=coeff(lhs(Kv1),t^2);
[ A := 2a(1, 2)uv + 2a(1, 3)uw + 2a(2, 3)vw + a(1, 1)u^2 + a(2, 2)v^2 + a(3, 3)w^2
[ > B:=1/2*coeff(lhs(Kv1),t);
[ B := a(1, 1)mu + a(1, 2)mv + a(1, 2)un + a(1, 3)mw + a(1, 3)up + a(2, 2)nv
[ + a(2, 3)nw + a(2, 3)vp + a(3, 3)pw + a(1, 4)u + a(2, 4)v + a(3, 4)w
[ > C:=sort(coeff(lhs(Kv1),t,0),[r,s,u]);
[ C := a(1, 1)m^2 + 2a(1, 2)mn + 2a(1, 3)mp + a(2, 2)n^2 + 2a(2, 3)np + a(3, 3)p^2
[ + 2a(1, 4)m + 2a(2, 4)n + 2a(3, 4)p + a(4, 4)
[ > B1:=collect(B,[u,v,w]);
[ B1 := (a(1, 1)m + a(1, 3)p + a(1, 4) + a(1, 2)n)u
[ + (a(1, 2)m + a(2, 2)n + a(2, 4) + a(2, 3)p)v

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+ (a(3, 3) p + a(2, 3) n + a(1, 3) m + a(3, 4)) w
> a1:=sort(coeff(B1,u),[m,n,p]); b1:=sort(coeff(B1,v),[m,n,p]);
c1:=sort(coeff(B1,w),[m,n,p]);
d1:=sort(coeff(coeff(B1,u,0),v,0),w,0),[m,n,p]);
a1 := a(1, 1) m + a(1, 2) n + a(1, 3) p + a(1, 4)
b1 := a(1, 2) m + a(2, 2) n + a(2, 3) p + a(2, 4)
c1 := a(1, 3) m + a(2, 3) n + a(3, 3) p + a(3, 4)
d1 := 0
> B2:=collect(B,[m,n,p]);
B2 := (a(1, 1) u + a(1, 2) v + a(1, 3) w) m + (a(1, 2) u + a(2, 2) v + a(2, 3) w) n
+ (a(2, 3) v + a(3, 3) w + a(1, 3) u) p + a(3, 4) w + a(1, 4) u + a(2, 4) v
> ra:=sort(coeff(B2,m),[u,v,w]); rb:=sort(coeff(B2,n),[u,v,w]);
rc:=sort(coeff(B2,p),[u,v,w]);
rd:=sort(coeff(coeff(B2,m,0),n,0),p,0),[u,v,w]);
ra := a(1, 1) u + a(1, 2) v + a(1, 3) w
rb := a(1, 2) u + a(2, 2) v + a(2, 3) w
rc := a(1, 3) u + a(2, 3) v + a(3, 3) w
rd := a(1, 4) u + a(2, 4) v + a(3, 4) w
> U:=Vector[row]([u,v,w,0]);
U := [u, v, w, 0]
> PrumerR:=collect(expand(evalm(U&*K&*Transpose(X))),[x,y,z])=0;
PrumerR := (a(1, 1) u + a(1, 2) v + a(1, 3) w) x + (a(1, 2) u + a(2, 2) v + a(2, 3) w) y
+ (a(1, 3) u + a(2, 3) v + a(3, 3) w) z + a(1, 4) u + a(2, 4) v + a(3, 4) w = 0
> n:=[coeff(lhs(PrumerR),x),coeff(lhs(PrumerR),y),coeff(lhs(PrumerR),z)];
n := [a(1, 1) u + a(1, 2) v + a(1, 3) w, a(1, 2) u + a(2, 2) v + a(2, 3) w,
a(1, 3) u + a(2, 3) v + a(3, 3) w]

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Dosadíme hodnoty parametrů dle zadání:

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> kv:=3*x^2+3*y^2+3*z^2+4*sqrt(2)*x*y+2*y*z+6*x+2*y*(2*sqrt(2)-1)-
6*z-9=0;
kv := 3 x2 + 3 y2 + 3 z2 + 4 √2 x y + 2 y z + 6 x + 2 y (2 √2 - 1) - 6 z - 9 = 0
> a(1,1):=coeff(lhs(kv),x^2); a(2,2):=coeff(lhs(kv),y^2);
a(3,3):=coeff(lhs(kv),z^2);
a(1,2):=1/2*coeff(coeff(lhs(kv),x),y);
a(1,3):=1/2*coeff(coeff(lhs(kv),x),z);
a(1,4):=1/2*coeff(coeff(coeff(lhs(kv),x,1),y,0),z,0);
a(2,3):=1/2*coeff(coeff(lhs(kv),y,1),z);
a(2,4):=1/2*coeff(coeff(coeff(lhs(kv),y,1),x,0),z,0);
a(3,4):=1/2*coeff(coeff(coeff(lhs(kv),z,1),y,0),x,0);
a(4,4):=coeff(coeff(coeff(lhs(kv),x,0),y,0),z,0);
a(1, 1) := 3

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a(2, 2) := 3
a(3, 3) := 3
a(1, 2) :=  $2\sqrt{2}$ 
a(1, 3) := 0
a(1, 4) := 3
a(2, 3) := 1
a(2, 4) :=  $2\sqrt{2} - 1$ 
a(3, 4) := -3
a(4, 4) := -9

> K;

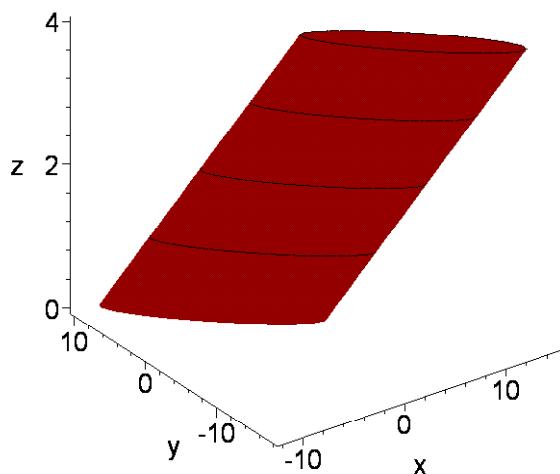
$$\begin{bmatrix} 3 & 2\sqrt{2} & 0 & 3 \\ 2\sqrt{2} & 3 & 1 & 2\sqrt{2} - 1 \\ 0 & 1 & 3 & -3 \\ 3 & 2\sqrt{2} - 1 & -3 & -9 \end{bmatrix}$$


> kv;

$$3x^2 + 3y^2 + 3z^2 + 4\sqrt{2}xy + 2yz + 6x + 2y(2\sqrt{2} - 1) - 6z - 9 = 0$$


> kvg:=plots[implicitplot3d](kv,x=-12..15,y=-18..10,z=0..4,axes=frame,color=red,style=patchcontour,grid=[40,40,10],lightmodel=light1,tickmarks=[3,3,3],orientation=[52,63],scaling=constrained,contours=5):
> display(kvg,axes=frame,scaleing=unconstrained,orientation=[-126,60]);

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> n;
[3u + 2 $\sqrt{2}$ v, 2 $\sqrt{2}$ u + 3v + w, v + 3w]

> uv:=[u,v,w];
uv := [u, v, w]

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> r:=evalm(n-lambda*uv);
       $r := [3u + 2\sqrt{2}v - \lambda u, 2\sqrt{2}u + 3v + w - \lambda v, v + 3w - \lambda w]$ 
> ChM:=linalg[genmatrix]([r[1],r[2],r[3]],[u,v,w]);
       $ChM := \begin{bmatrix} 3-\lambda & 2\sqrt{2} & 0 \\ 2\sqrt{2} & 3-\lambda & 1 \\ 0 & 1 & 3-\lambda \end{bmatrix}$ 
> ChR:=linalg[det](ChM)=0;
       $ChR := -18\lambda + 9\lambda^2 - \lambda^3 = 0$ 
> collect(ChR,[lambda^3,lambda^2,lambda]);
       $-18\lambda + 9\lambda^2 - \lambda^3 = 0$ 
> I1:=coeff(lhs(ChR),lambda,2);
       $I1 := 9$ 
> I2:=coeff(lhs(ChR),lambda,1);
       $I2 := -18$ 
> A44:=coeff(lhs(ChR),lambda,0);
       $A44 := 0$ 
> Delta:=linalg[det](K);
       $\Delta := 0$ 
> lambda_sol:=solve(ChR,{lambda});
       $lambda\_sol := \{\lambda = 0\}, \{\lambda = 6\}, \{\lambda = 3\}$ 
> r1:=eval(r,lambda_sol[1]); r2:=eval(r,lambda_sol[2]);
r3:=eval(r,lambda_sol[3]);
       $r1 := [3u + 2\sqrt{2}v, 2\sqrt{2}u + 3v + w, v + 3w]$ 
       $r2 := [-3u + 2\sqrt{2}v, 2\sqrt{2}u - 3v + w, v - 3w]$ 
       $r3 := [2\sqrt{2}v, 2\sqrt{2}u + w, v]$ 
> hs1:=eval(uv,solve({r1[1],r1[2],r1[3]},{u,v,w}));
hs2:=eval(uv,solve({r2[1],r2[2],r2[3]},{u,v,w}));
hs3:=eval(uv,solve({r3[1],r3[2],r3[3]},{u,v,w}));
       $hs1 := [2\sqrt{2}w, -3w, w]$ 
       $hs2 := [2\sqrt{2}w, 3w, w]$ 
       $hs3 := [u, 0, -2\sqrt{2}u]$ 
> PrumerR;
       $(3u + 2\sqrt{2}v)x + (2\sqrt{2}u + 3v + w)y + (v + 3w)z + 3u + (2\sqrt{2} - 1)v - 3w = 0$ 
> Smer1:=eval(hs1,{u=1,v=1,w=1});
       $Smer1 := [2\sqrt{2}, -3, 1]$ 
> PrumerR1:=eval(PrumerR,[u=Smer1[1],v=Smer1[2],w=Smer1[3]]);
       $PrumerR1 := 0 = 0$ 
> Smer2:=eval(hs2,{u=1,v=1,w=1});
       $Smer2 := [2\sqrt{2}, 3, 1]$ 
> PrumerR2:=eval(PrumerR,[u=Smer2[1],v=Smer2[2],w=Smer2[3]]);

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PrumerR2 :=  $12\sqrt{2}x + 18y + 6z + 12\sqrt{2} - 6 = 0$ 
> Smer3:=eval(hs3,{u=1,v=1,w=1});  

Smer3 := [1, 0,  $-2\sqrt{2}$ ]
> PrumerR3:=eval(PrumerR,[u=Smer3[1],v=Smer3[2],w=Smer3[3]]);  

PrumerR3 :=  $3x + 3 - 6\sqrt{2}z + 6\sqrt{2} = 0$ 
> col2:=blue:  

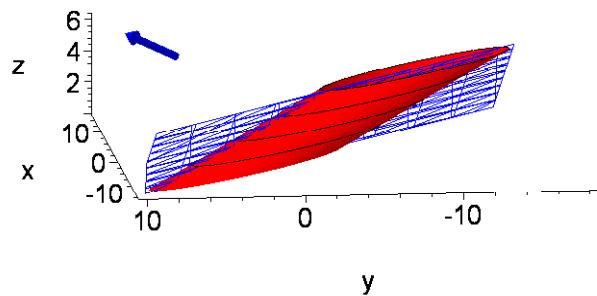
> PrumerR2g:=implicitplot3d(PrumerR2,x=-12..15,y=-18..10,z=0..4,gr  

id=[10,10,10],style=wireframe,color=col2):
> Smer2g:=plottools[arrow]([8, 6, 5], vector(Smer2), 0.5, 1, 0.2,  

cylindrical_arrow,color=col2):
> display(kvg,PrumerR2g,Smer2g,axes=frame,scaling=constrained,orie  

ntation=[173,78],light=[50,45,1,1,1]);

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> col3:=green:  

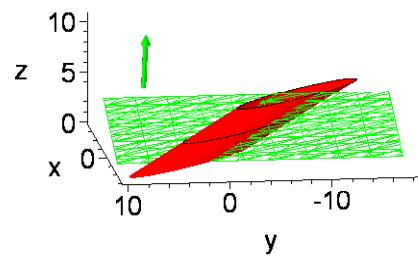
> PrumerR3g:=implicitplot3d(PrumerR3,x=-12..15,y=-18..10,z=0..4,gr  

id=[10,10,10],style=wireframe,color=col3):
> Smer3g:=plottools[arrow]([8,6,5], vector(-2*Smer3), 0.5, 1, 0.2,  

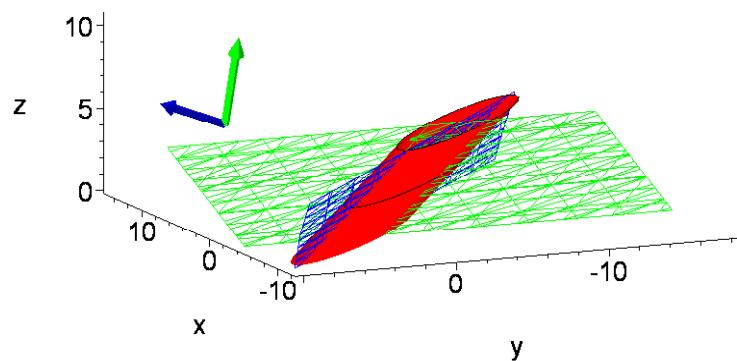
cylindrical_arrow,color=col3):
> display(kvg,PrumerR3g,Smer3g,axes=frame,scaling=constrained,orie  

ntation=[173,78],light=[50,45,1,1,1]);

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> display(kvg,PrumerR2g,Smer2g,PrumerR3g,Smer3g,axes=frame,scaling=constrained,orientation=[153,78],light=[50,45,1,1,1]);
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[>  
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